

1 RESEARCH ARTICLE

2 How to use the Development (DEV) L<sup>A</sup>T<sub>E</sub>X class

3 First author<sup>1</sup> and Second author<sup>2</sup>

4

5 ABSTRACT

6 This sample is a guideline for preparing technical papers using  
 7 L<sup>A</sup>T<sub>E</sub>X for DEV manuscript submission. It contains the documenta-  
 8 tion for COB L<sup>A</sup>T<sub>E</sub>X class file, which implements the layout of  
 9 the manuscript for DEV journal. This sample file uses a class  
 10 file named COB.cls where the authors should use during their  
 11 manuscript preparation.  
 12

13 KEYWORDS: keyword entry 1, keyword entry 2, keyword entry 3

15 INSERT A HEAD HERE

16 This demo file is intended to serve as a “starter file” for Develop-  
 17 ment papers produced under L<sup>A</sup>T<sub>E</sub>X using COB.cls.

18 Insert B head here

19 Subsection text here.

20 Insert C head here

21 Subsubsection text here.

22 EQUATIONS

23 Sample equations.

$$\begin{aligned}
 \frac{\partial u(t, x)}{\partial t} &= Au(t, x) \left( 1 - \frac{u(t, x)}{K} \right) \\
 &\quad - B \frac{u(t - \tau, x)w(t, x)}{1 + Eu(t - \tau, x)}, \\
 \frac{\partial w(t, x)}{\partial t} &= \delta \frac{\partial^2 w(t, x)}{\partial x^2} - Cw(t, x) \\
 &\quad + D \frac{u(t - \tau, x)w(t, x)}{1 + Eu(t - \tau, x)},
 \end{aligned}
 \tag{1}$$

$$\begin{aligned}
 \frac{dU}{dt} &= \alpha U(t)(\gamma - U(t)) - \frac{U(t - \tau)W(t)}{1 + U(t - \tau)}, \\
 \frac{dW}{dt} &= -W(t) + \beta \frac{U(t - \tau)W(t)}{1 + U(t - \tau)}.
 \end{aligned}
 \tag{2}$$

$$\begin{aligned}
 \frac{\partial(F_1, F_2)}{\partial(c, \omega)} \Big|_{(c_0, \omega_0)} &= \begin{vmatrix} \frac{\partial F_1}{\partial c} & \frac{\partial F_1}{\partial \omega} \\ \frac{\partial F_2}{\partial c} & \frac{\partial F_2}{\partial \omega} \end{vmatrix} \Big|_{(c_0, \omega_0)} \\
 &= -4c_0q\omega_0 - 4c_0\omega_0p^2 = -4c_0\omega_0(q + p^2) > 0.
 \end{aligned}$$

ENUNCIATIONS

**Theorem 1.** Assume that  $\alpha > 0, \gamma > 1, \beta > \frac{\gamma+1}{\gamma-1}$ . Then there exists a small  $\tau_1 > 0$ , such that for  $\tau \in [0, \tau_1)$ , if  $c$  crosses  $c(\tau)$  from the direction of to a small amplitude periodic traveling wave solution of (2.1), and the period of  $(\tilde{u}^P(s), \tilde{w}^P(s))$  is

$$\tilde{T}(c) = c \cdot \left[ \frac{2\pi}{\omega(\tau)} + O(c - c(\tau)) \right].
 \tag{35}$$

**Condition 1.** From (0.8) and (2.10), it holds  $\frac{d\omega}{d\tau} < 0, \frac{dc}{d\tau} < 0$  for  $\tau \in [0, \tau_1)$ . This fact yields that the system (2.1) with delay  $\tau > 0$  has the periodic traveling waves for smaller wave speed  $c$  than that the system (2.1) with  $\tau = 0$  does. That is, the delay perturbation stimulates an early occurrence of the traveling waves.

$$\tilde{T}(c) = c \cdot \left[ \frac{2\pi}{\omega(\tau)} + O(c - c(\tau)) \right].
 \tag{41}$$

**Remark 1.** From (0.8) and (2.10), it holds  $\frac{d\omega}{d\tau} < 0, \frac{dc}{d\tau} < 0$  for  $\tau \in [0, \tau_1)$ . This fact yields that the system (2.1) with delay  $\tau > 0$  has the periodic traveling waves for smaller wave speed  $c$  than that the system (2.1) with  $\tau = 0$  does. That is, the delay perturbation stimulates an early occurrence of the traveling waves.

$$\tilde{T}(c) = c \cdot \left[ \frac{2\pi}{\omega(\tau)} + O(c - c(\tau)) \right].
 \tag{47}$$

**Lemma 1.** From (0.8) and (2.10), it holds  $\frac{d\omega}{d\tau} < 0, \frac{dc}{d\tau} < 0$  for  $\tau \in [0, \tau_1)$ . This fact yields that the system (2.1) with delay  $\tau > 0$  has the periodic traveling waves for smaller wave speed  $c$  than that the system (2.1) with  $\tau = 0$  does. That is, the delay perturbation stimulates an early occurrence of the traveling waves.

$$\tilde{T}(c) = c \cdot \left[ \frac{2\pi}{\omega(\tau)} + O(c - c(\tau)) \right].
 \tag{53}$$

**Proposition 1.** From (0.8) and (2.10), it holds  $\frac{d\omega}{d\tau} < 0, \frac{dc}{d\tau} < 0$  for  $\tau \in [0, \tau_1)$ . This fact yields that the system (2.1) with delay  $\tau > 0$  has the periodic traveling waves for smaller wave speed  $c$  than that the system (2.1) with  $\tau = 0$  does. That is, the delay perturbation stimulates an early occurrence of the traveling waves.

$$\tilde{T}(c) = c \cdot \left[ \frac{2\pi}{\omega(\tau)} + O(c - c(\tau)) \right].
 \tag{59}$$

FIGURES & TABLES

The output for figure is:

An example of a double column floating figure using two sub-figures. (The subfig.sty package was already included in the class file.) The subfigure \label commands are set within each subfloat command, the \label for the overall figure must come after

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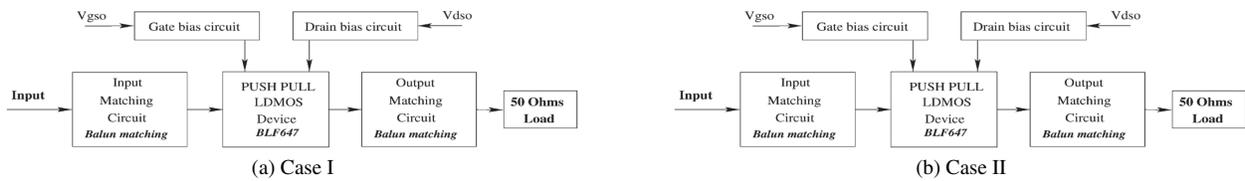


Fig. 1. Sample sub figures in L<sup>A</sup>T<sub>E</sub>X

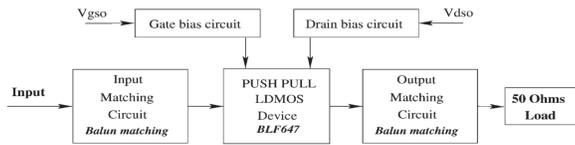


Fig. 2. Insert figure caption here

66 \caption. \hfil must be used as a separator to get equal spac-  
 67 ing. The subfigure.sty package works much the same way, except  
 68 \subfigure is used instead of \subfloat.

69 The output for table is:

**Table 1.** An Example of a Table

Head 1	Head 2	Head 3	Head 4	Head 5
One	Two	Three	Four	Five
Six	Seven	Eight	Nine	Ten

70 **CONCLUSION**

71 The conclusion text goes here.

72 **Acknowledgements**

73 Insert the Acknowledgment text here.

74 **Competing interests**

75 Insert the Competing interests text here.

**Contribution**

Insert the Contribution text here.

**Funding**

Insert the Funding interests text here.

**Data availability**

Insert the Data availability text here.

**Supplementary**

Insert the supplementary text text here.

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